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(56) Documents Cited

GB 2352321 A	GB 2352150 A
GB 2280577 A	WO 96/23368 A
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(54) Abstract Title

RF communication with downhole equipment

(57) Data or control signals are communicated over all phases of a three phase power cable 104 supplying power from a surface location to a motor/pump assembly 106 located within a wellbore utilizing modulated radio frequency signals. The radio frequency signals may be impressed on the power cable through physical taps to the power cable conductors or by reactive coupling to the power cable. The transmission frequency is selected from a range of frequencies which propagate through the motor windings and up the power cable with sufficient amplitude to be received and processed. The modulated RF signal may be transmitted concurrently with the three phase power on the power cable, and simultaneous bidirectional communications between the surface and downhole locations may be supported utilizing, for example, discrete frequencies for transmission in different directions. A network of RF transceivers or nodes 114a-114f may be situated at various locations along the wellbore and the motor/pump assembly to gather information about conditions at different points (e.g., below the motor/pump assembly, above the motor/pump assembly, and at the wellhead of a subsea borehole), with transmission on the power cable shared among the nodes through a spread spectrum and/or multiple access protocol.

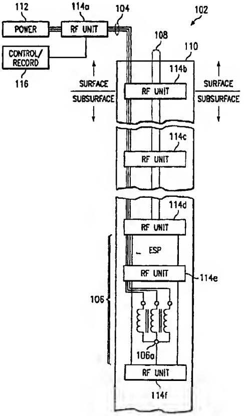

FIG. 1

GB 2 369 759 A

At least one drawing originally filed was informal and the print reproduced here is taken from a later filed formal copy.

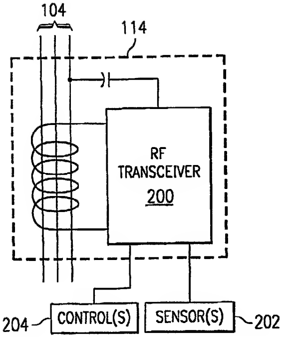
104
114
RF
TRANSCEIVER
200
204
CONTROL(S)
SENSOR(S)
202

FIG. 2

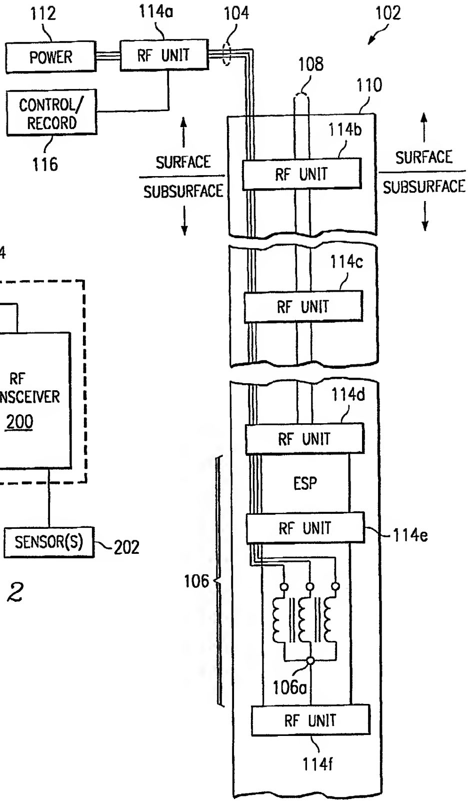
112
114a
104
102
POWER
RF UNIT
CONTROL/
RECORD
116
108
110
114b
RF UNIT
SURFACE
SUBSURFACE
SURFACE
SUBSURFACE
114c
RF UNIT
114d
RF UNIT
ESP
RF UNIT
114e
106
106a
RF UNIT
114f

FIG. 1

RF COMMUNICATION WITH DOWNHOLE EQUIPMENT

RELATED APPLICATIONS

The present invention is a continuation-in-part of commonly assigned, co-pending U.S. patent application serial no. 09/029,732 entitled "AN IMPROVED ELECTRICAL SUBMERSIBLE PUMP AND METHODS FOR ENHANCED UTILIZATION OF ELECTRICAL SUBMERSIBLE PUMPS IN THE COMPLETION AND PRODUCTION OF WELLBORES" and filed February 8, 1999. The content of the above-identified application is incorporated herein by reference.

BACKGROUND OF THE INVENTION

1. Technical Field:

The present invention generally relates to data telemetry systems for downhole sensors and other equipment and in particular to data telemetry over power cables. Still more particularly, the present invention relates to employing a modulated radio frequency carrier for data telemetry over power cables.

2. Description of the Related Art:

Various data telemetry systems for returning measurements from sensors within a borehole or for transmitting commands to equipment within the borehole have been proposed and/or utilized. Several such systems employ the power cable transmitting three phase power downhole to

an electrical submersible pump or other load device for transmitting the telemetry signals. Within these types of systems, generally the signaling arrangement either requires a ground reference for the return path or treats all three power conductor cables as a single conductor.

Systems which require a ground reference usually require an additional conductor for the return path. However, casing and tubing dimensions may not leave enough room for the additional conductor, the additional conductor adds to the cost of the system, and the additional conductor represents an additional point of possible failure for the system.

On the other hand, systems which treat the three phase power cable as a single conductor often cannot tolerate a ground reference--either intentional or inadvertent--within the power system. Thus, for example, if one phase or conductor of the power system should accidentally be shorted to ground, the downhole components which rely on the three-phase power (e.g., the pump) continue to operate while the telemetry system is disabled.

Moreover, systems employing the three phase power system for data telemetry are frequently limited to one receiving/transmitting device downhole, although it would often be useful to obtain data measurements at several locations within the borehole. In particular, data telemetry systems employing the three phase power cable powering a downhole motor and pump are generally positioned above the motor/pump assembly. Such measurements may be of limited value regarding the operation of the pump, which may

extend for a significant distance down the borehole from the top of the motor/pump assembly.

In particular, when an electrical submersible pump (ESP) is employed, the motor/pump assembly is often as long as 60-70 feet, and may be as long as 90-100 feet. Measurements taken at the top of such a motor/pump assembly are not necessarily indicative of conditions at the bottom of the assembly. Measurements for a variety of conditions at the bottom of the motor and/or the bottom of the pump may be useful in monitoring or controlling operations, such as intake pressure and temperature, vibration, flow rate, revolutions per minute, winding temperature, discharge pressure and temperature, and "water cut" (oil/water mixture).

It would be desirable, therefore, to provide a telemetry system employing three-phase power conductors for the data signals without requiring a return or ground reference conductor, but fault-tolerant with respect to unintentional grounding of one or two power phases. It would further be advantageous to provide a data telemetry system which allowed the use of multiple receiving and transmitting stations within the borehole.

SUMMARY OF THE INVENTION

Data or control signals are communicated over a three phase power cable supplying power from a surface location to a motor/pump assembly located within a wellbore utilizing modulated radio frequency signals. The radio frequency signals may be impressed on the power cable through physical taps to the power cable conductors or by reactive coupling to the power cable. The transmission frequency is selected from a range of frequencies which propagate through the motor windings and up the power cable with sufficient amplitude to be received and processed. The modulated RF signal may be transmitted concurrently with the three phase power on the power cable, and simultaneous bidirectional communications between the surface and downhole locations may be supported utilizing, for example, discrete frequencies for transmission in different directions. A network of RF transceivers or nodes may be situated at various locations along the wellbore and the motor/pump assembly to gather information about conditions at different points (e.g., below the motor/pump assembly, above the motor/pump assembly, and at the wellhead of a subsea borehole), with transmission on the power cable shared among the nodes through a spread spectrum and/or multiple access protocol.

The above as well as additional objectives, features, and advantages of the present invention will become apparent in the following detailed written description.

BRIEF DESCRIPTION OF THE DRAWINGS

The novel features believed characteristic of the invention are set forth in the appended claims. The invention itself however, as well as a preferred mode of use, further objects and advantages thereof, will best be understood by reference to the following detailed description of an illustrative embodiment when read in conjunction with the accompanying drawings, wherein:

Figure 1 depicts a data telemetry system in accordance with a preferred embodiment of the present invention; and

Figure 2 is a radio frequency data telemetry unit in accordance with a preferred embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

With reference now to the figures, and in particular with reference to **Figure 1**, a data telemetry system in accordance with a preferred embodiment of the present invention is depicted. The data telemetry system **102** includes a three phase power cable **104** having separate conductors for each phase. Three phase power cable **104** is connected to a motor and pump assembly **106** adapted for use within a bore hole and disposed within the bore hole by connection to tubing **108** lowered within the casing **110** for a well. Pump and motor assembly **106** may include an electrical submersible pump (ESP), such as the type disclosed in U.S. Patent 5,845,709, coupled to a motor (e.g., an induction motor). The motor drives the pump and is powered by three phase power transmitted over three phase transmission cable **104** electrically coupling pump and motor assembly **106** to a surface power source **112**.

Three phase transmission cable 104 transmits three phase power from a surface power system **112**. Surface power system may be any suitable three phase power system such as an inverter, a motor or turbine driven generator and/or an alternator producing three phase alternating current of about 380 to 5,000 volts (RMS) at a typical frequency of 30-90 Hz.

Sensors within the bore hole measure selected parameters such as temperature, pressure, and/or flow rate and generate electrical signals representative of the

measurements. Additionally, controls for controlling the operation of motor/pump assembly **106** may also be configured to receive control signals from the surface. In the present invention, such measurement and control signals are transmitted over the conductors of three phase power cable **104** in a radio frequency signal. The data and control signal telemetry are performed utilizing radio frequency (RF) units **114a-114f** positioned at various locations along the borehole.

Referring to **Figure 2**, a radio frequency data telemetry unit in accordance with a preferred embodiment of the present invention is illustrated. It has been determined that radio frequency (RF) energy will, for selected frequency ranges dependent upon the motor and cable configuration, propagate through a downhole motor and up the power cable with sufficient amplitude to be received and processed. Some frequencies transmit through with more energy than others. Suitable frequencies for a particular motor and cable configurations may be determined experimentally, either through physical tests or through simulations. Frequencies in the range of 1-3 MHZ are believed to be generally suitable for most common ESP motor and cable configurations, although frequencies of as low as 550 KHz or as high as 10 MHZ may also be suitable. The frequency 1.8 MHZ has been successfully used with Centrilift series 562 motors connected to a three phase power cable.

At these frequencies, which propagate through a downhole motor and up the power cable with sufficient amplitude to be detected at the surface, information may be

transmitted in both directions between the surface and the equipment within the well by modulating the RF carrier either with continuous linear signals or, preferably, with encoded information. Modulation of frequency, phase, amplitude, or any combination of the three may be employed to transmit information using the RF carrier. Accordingly, frequency modulation (FM), amplitude modulation (AM), frequency shift key (FSK) modulation, phase shift key (PSK) modulation, and other similar forms of modulation may be employed.

Each RF unit **114a-114f** depicted in **Figure 1** preferably includes an RF transceiver **200**. For some locations along the borehole, where measurements are taken, an RF transmitter alone may be sufficient. Similarly, an RF receiver alone may be employed at the surface, or at other selected locations (e.g., employing discrete RF transmitters and RF receivers at the motor/pump assembly). Preferably, however, each RF unit includes an RF transceiver **200** capable of both transmission and reception, so that multiple nodes along the borehole may be "addressed" as described below.

RF transceiver **200** operates according to conventional radio frequency transmission and reception technology, except for the specific requirements noted herein. RF receiver **200** may have an independent, internal power source, such as a battery, or may be connected to one or more conductors of the three phase power cable **104** for power. RF transceiver **200** receives and transmits RF signals on power cable **104**. RF transceiver **200** may thus be directly

connected to power cable **104** through a tap. Such a connection may be preferable at some locations within the borehole, such as at the motor, where a connection may be made to a neutral (Y) point **106a** (**Figure 1**) commonly found in downhole motors. In any location along the borehole or at the motor neutral, however, RF transceiver is preferably reactively coupled to power cable **104** by single or multiple capacitive sleeving around the power conductors and connected via an appropriate inductance so as to series resonate at the carrier frequency.

RF transceiver **200** is connected to one or more sensors **202** measuring desired parameters such as intake pressure and temperature, vibration, flow rate, revolutions per minute, winding temperature, discharge pressure and temperature, and water cut. The parameter measurements are preferably converted to digital representations, which are employed to encode the information, together with any requisite control signals, within the RF signal by modulating the RF carrier. The parameter measurement information and control signals are transmitted through the motor and along the power cable to the surface, where the measurement information and control signals may be extracted from the RF signal received over the power cable by demodulation.

RF transceiver **200** may also be connected to one or more controls **204** controlling operation of the motor and pump assembly. Control signals from a surface control unit may be encoded within the RF carrier signal by modulation and transmitted from the surface downhole along the power cable, and extracted from the RF signal received at the motor/pump

assembly by demodulation. Upon detection by controls **204**, the commands represented by such control signals (e.g., operating valves or other downhole equipment, or setting data acquisition configuration or downhole transmitter frequency) may be executed.

Referring back to **Figure 1**, a network of RF units **114a-114f** may be employed at various locations relative to a wellbore all commonly connected by the three phase power cable **104**. A surface RF unit **114a** located proximate to the power source **112** may be utilized to receive parameter measurements from other units located within the wellbore and to transmit control signals to other units within the wellbore. A second surface unit **114b** may be located at the wellhead, particularly for subsea wells, where wellhead pressure, temperature, and cut may be measured and transmitted to the control system **116**. One or more additional RF units **114c** may be located at various intervals within the wellbore **110**, providing selected measurements useful for controlling pumping operations. An RF unit **114d** may be situated at the top of the motor/pump assembly **106**, with a second RF unit **114e** located at the connection between the motor and pump, at the seal section of motor/pump assembly **114f**, and a third RF unit **114f** situated at the bottom of motor/pump assembly **106**.

RF units **114a-114f** may operate bidirectionally, both transmitting and receiving RF signals over power cable **104**. Transmission on power cable **104** may be sequentially

multiplexed, either by negotiating for access employing a carrier sense multiple access with collision detect (CSMA/CD) algorithm or being allocated a time slice of the available bandwidth employing a time division multiple access (TDMA) protocol.

RF units **114a-114f** may also operate simultaneously, with several units transmitting and receiving at the same time or any unit both transmitting and receiving simultaneously. Two distinct frequencies may be employed, one for transmission from the surface downhole and another for transmission in the opposite direction, with RF units **114b-114f** addressed by the control system **116** through RF unit **114a** and activated in response to an assigned code. Each RF unit **114a-114f** may alternatively be assigned a separate frequency to allow simultaneous bidirectional communication, with each downhole RF unit **114b-114f** employing one or more discrete frequencies for transmission and reception and only the RF unit **114a** connected to the control system **116** receiving and transmitting on all of those frequencies. Alternatively, spread spectrum technologies employing a code division multiple access (CDMA) protocol or frequency hopping may be utilized to enable simultaneous bidirectional communication between the surface RF unit **114a** and other nodes **114b-114f** along the power cable **104**.

With the present invention, no return ground conductor is required, although one or more phases of power cable **104** may be grounded--either intentionally or inadvertently--and

communications between the surface and downhole locations may be maintained. Additionally, communications over the power cable are possible while the motor/pump assembly are being lowered downhole. Information may be transmitted through the motor windings from the bottom of the motor/pump assembly and propagate up the power cable to the surface.

While the invention has been particularly shown and described with reference to a preferred embodiment, it will be understood by those skilled in the art that various changes in form and detail may be made therein without departing from the spirit and scope of the invention.

CLAIMS:

What is claimed is:

1. A method of communication over a power cable, comprising:

transmitting power over a three phase power cable connecting surface equipment to downhole components;

transmitting a radio frequency signal over the power cable concurrently with the power; and

decoupling the radio frequency signal from the power received over the power cable.

2. The method of claim 1, wherein the step of transmitting a radio frequency signal over all phases of the power cable concurrently with the power further comprises:

transmitting the radio frequency signal through a pump motor.

3. The method of claim 1, wherein the step of transmitting a radio frequency signal over all phases of the power cable concurrently with the power further comprises:

modulating the frequency, phase, amplitude, or a combination of frequency, phase, and amplitude of the radio frequency signal to encode information within the radio frequency signal.

4. The method of claim 1, wherein the step of transmitting a radio frequency signal over all phases of the power cable concurrently with the power further comprises:

transmitting data from the downhole components to the surface equipment.

5. A system for communication over a power cable, comprising:

a three phase power cable transmitting power from surface equipment to downhole components;

an electrical submersible pump coupled to the power cable and receiving power from the power cable;

a first transceiver transmitting a radio frequency signal over all phases of the power cable concurrently with the power; and

a second transceiver decoupling the radio frequency signal from the power received over the power cable.

6. The system of claim 5, wherein a motor for the electrical submersible pump is disposed between the first and second transceivers and the radio frequency signal is transmitted across the electrical submersible pump motor.

Application No:	GB 0117426.7	**Examiner:**	Martyn Dixon
Claims searched:	all	**Date of search:**	8 April 2002

Patents Act 1977
Search Report under Section 17

Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK Cl (Ed.T): H4R (RTSR,RTSU,RTT,RTR,RTC); E1F (FHK)

Int Cl (Ed.7): E21B (47/12); G08C (19/12,19/14,19/16); H04B (3/54,3/56)

Other: Online: EPODOC,WPI,JAPIO

Documents considered to be relevant:

Category	Identity of document and relevant passage		Relevant to claims
X,P	GB 2352321 A	(Baker Hughes) see fig 1, page 4, lines 5-18 and page 6, line 10 to page 7, line 5	1,4,5
X,P	GB 2352150 A	(Axon) see especially figs 5 and 8	1-6
X	GB 2280577 A	(Schlumberger) the whole document	1,3-5
X,E	WO 01/86831 A	(Baker Hughes) see the whole document	1,3-5
X	WO 96/23368 A	(TSL Technology *et al*) see e.g. page 14, line 33 to page 15, line 14	1,3-5
X	US 4157535 A	(Lynes) see fig 1	1-6

X	Document indicating lack of novelty or inventive step	A	Document indicating technological background and/or state of the art.
Y	Document indicating lack of inventive step if combined with one or more other documents of same category.	P	Document published on or after the declared priority date but before the filing date of this invention.
&	Member of the same patent family	E	Patent document published on or after, but with priority date earlier than, the filing date of this application.